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Spatially Continuous Interpolation of Water Stage and Water Depths Using the Everglades Depth Estimation Network (EDEN)¹

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Abstract

The Everglades Depth Estimation Network (EDEN) is an integrated network of real-time water-level monitoring, ground-elevation modeling, and water-surface modeling that provides scientists and managers with current (2000-present), on-line water-stage and water-depth information for the entire freshwater portion of the Greater Everglades. Continuous daily spatial interpolations of the EDEN network stage data are presented on a 400-square-meter grid spacing. EDEN offers a consistent and documented dataset that can be used by scientists and managers to (1) guide large-scale field operations, (2) integrate hydrologic and ecological responses, and (3) support biological and ecological assessments that measure ecosystem responses to the implementation of the Comprehensive Everglades Restoration Plan (CERP). The target users are biologists and ecologists examining trophic level responses to hydrodynamic changes in the Everglades.

Introduction

Spatially explicit hydrologic information can be critical in understanding and predicting changes in biotic communities in wetland ecosystems. In Florida's Everglades there have been numerous efforts to measure and link daily and seasonally fluctuating surface water depth to biotic communities. Repeated field measurement is a traditional way to obtain such information, but it is labor intensive and does not provide information on continuous spatial variability across a large area. Taking systematic field measurements across space and time is difficult since the Everglades comprise remote and inaccessible areas. Alternatively, hydrologic models are frequently used in ecological research in the Everglades (Walters et al. 1992; Curnutt et al. 2000; Immanuel et al. 2005).

Over 200 real-time stage monitoring gages have been placed throughout the Everglades by various agencies with different monitoring needs to automatically measure stage and radio-transmit the data. The Everglades Depth Estimation Network (EDEN) is funded by the Comprehensive Everglades Restoration Plan (CERP) and US Geological Survey (USGS) Priority Ecosystem Sciences (PES) with collaborative support between federal and state government agencies, scientists in south Florida, and University of Florida. This project integrates existing and new telemetered water-level gages into a single network and, in combination with high resolutions ground elevation modeling, generates a daily continuous water surface and water depth for the freshwater greater Everglades. This provides investigators with tools to infer other hydrologic characteristics such as recession rates, time since last dry period and water-surface slope.

This report documents the procedures used in generation of EDEN water stage and water depth interpolated surfaces.

Procedures

The water surface model follows the steps illustrated in Figure 1 and are detailed in this section:

1. Water-level data for all the EDEN gages are retrieved from an ftp server.
2. Water-level data reported in NGVD 29 are converted to NAVD 88
3. Daily median water level is calculated.
4. Linear interpolation is used to create boundary conditions along canals and levees.
5. Radial Basis Function multiquadric interpolation of extended data (median water level from gages in marsh and interpolated values along canals) is used to generate continuous water level surfaces daily.
6. The continuous water surface is predicted on the EDEN grid (400 m x 400 m).
7. Water depth is estimated by subtracting the EDEN ground digital elevation model (DEM) from the predicted water surface.

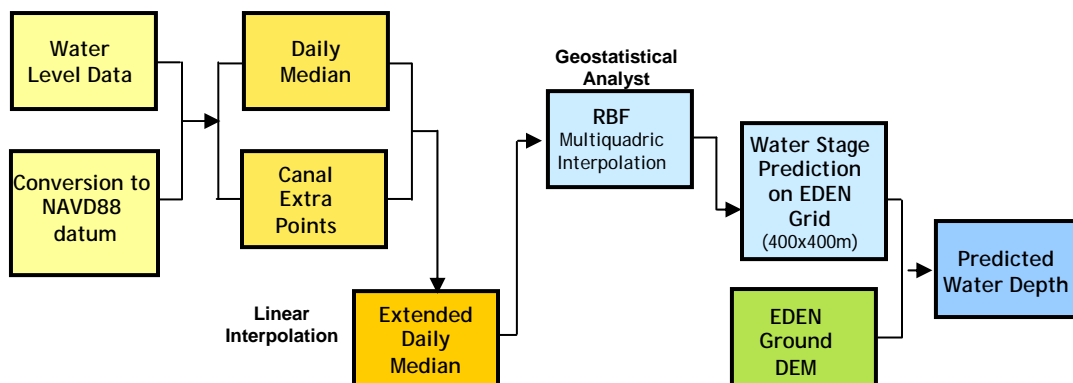


Figure 1. Flow chart of water stage and water depth modeling for EDEN.

The USGS retrieves water level data daily from 253 gaging stations including 225 telemetry-enhanced gages that record and transmit several water level values throughout the day, mostly hourly from recorders ranging approximately from 81°07'19W to 80°13'05W in easting and 25°13'27N to 26°40'47N in northing in south Florida. An additional 28 gages do not have telemetry and are manually read and added to the network (Figure 2 and Appendix A). All transmitted data are entered and stored in the National Water Information System (NWIS), a database operated by the United States Geological Survey (USGS). The 13 USGS gages in the EDEN network bordering the Gulf of Mexico are not used in the surfacing interpolations described in this report. There are a total of 240 gages used for water surface interpolation of the freshwater Everglades.

All gages in the EDEN network are operated and maintained by four separate agencies including Everglades National Park (ENP), South Florida Water Management District (SFWMD), Big Cypress National Preserve (BCNP), and the USGS. The NWIS database transmits all recorded data to a local USGS FTP server where it is available for surfacing. Gage data and its metadata are available for preview and downloading at the EDENweb (<http://sofia.usgs.gov/eden>).

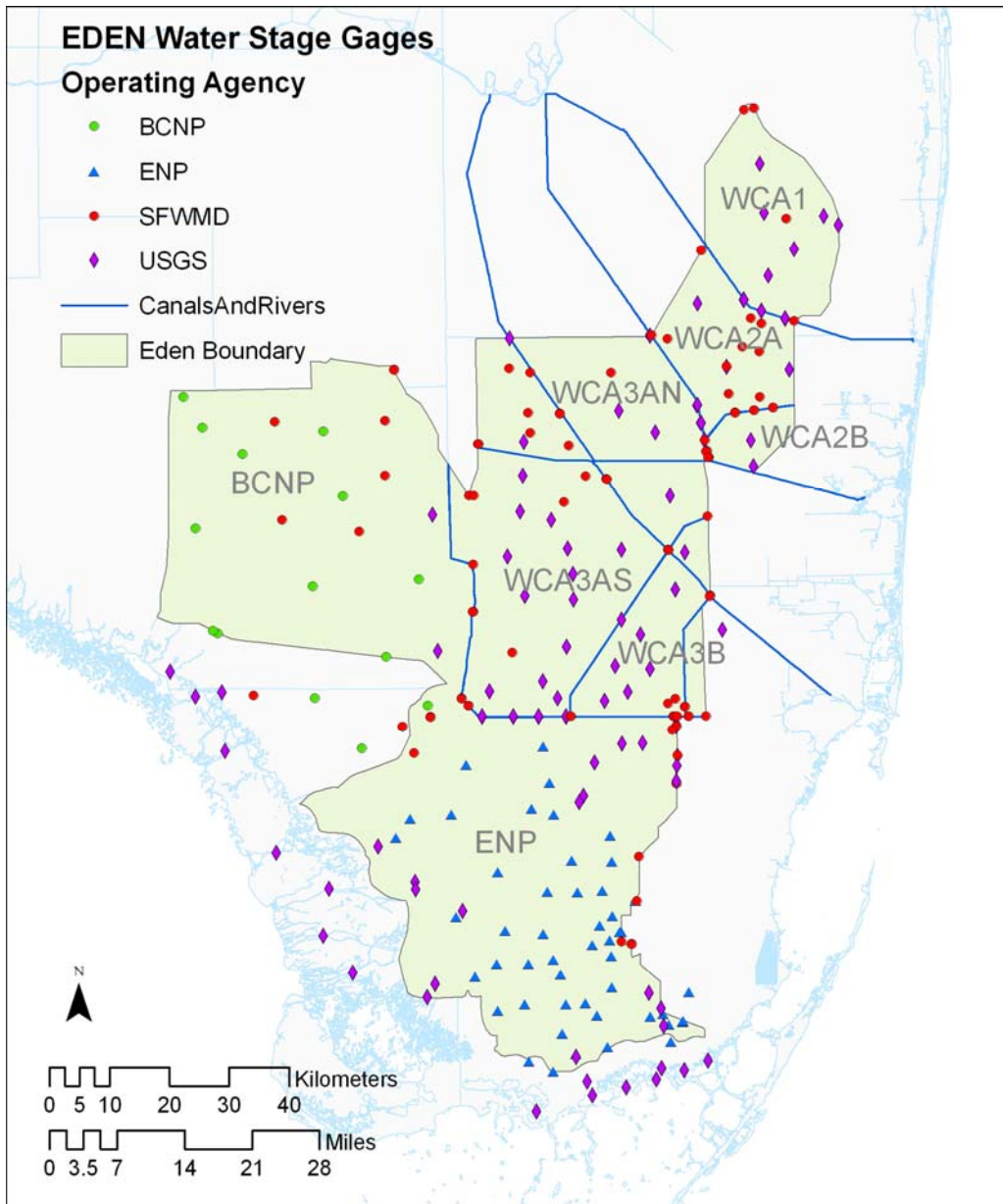


Figure 2. Location of water stage gages collected in the EDEN network. Water Conservation Areas (WCA) 2 and 3 are subdivided by canals. WCA3A is further subdivided into a northern (WCA3AN) and southern (WCA3AS) region.

The EDEN area is divided in 8 distinct sections by canals and levees, with 5 sections belonging to three distinct water conservation areas surrounded by canals and levees (Figure 2). Abrupt water level discontinuities among the sections complicate interpolation across the entire area. Water level near section boundaries is further influenced by the SFWMD's operation of massive pumps and canals to distribute water for natural areas, agriculture, urban use and flood protection.

The gaging stations fall generally into 2 categories: marsh stations (away from canals) and canal stations. In locations where canal stations are at a structure across a levee, gages are frequently paired so that there is a gage on both sides of the levee to measure differences in water stage created by the levee and structure. These paired gaging stations are referred to as “head” and “tail” stations (Figure 3). Canal stations may or may not have a continuous hydrologic connection with stations further out in the marsh.



Figure 3. Example of head and tail gaging stations at S-11C. S-11C is a control structure in the levee dividing Water Conservation Area 2A from Water Conservation Area 3A-North.

To prepare a range of dates for surfacing, data retrieved from gaging stations in National Geodetic Vertical Datum of 1929 (NGVD 29) is converted to North American

Vertical Datum of 1988 (NAVD 88) (Telis, 2006) and the median value for each day is calculated. Daily median values are used for the interpolation algorithm to reduce the influence of occasional incorrect extreme values in the data.

The canal and levee boundaries act as major discontinuities in the EDEN area, and water levels from one section have minimal or no influence into adjacent sections. Steep changes in elevation can occur between areas at these levees. Since stratification of the data is not feasible due to the limited number of water gages, boundary conditions were simulated by linearly interpolating along both sides of levels in the canals using head and tail stage data. Simulated data at these pseudo-stations were re-sampled every 200 m and re-introduced into the interpolation exercise (Figure 4). The marsh gage data together with the interpolated data along canals represent the new extended data used for water surface modeling. In this way, data from the marsh in one conservation area would not influence the values in the marsh across a canal in a different area. Even though track data (very densely sampled preferential lines) alone may be problematic for interpolation, our mixture of track data along canals and levees, plus randomly distributed stage data, and the provision to use only the closest data point to the interpolated location in each of the 8 sectors of a search neighborhood (see below) overcomes some of the problems. Nevertheless, we still place a reduced confidence in the interpolated surface close to canal data.

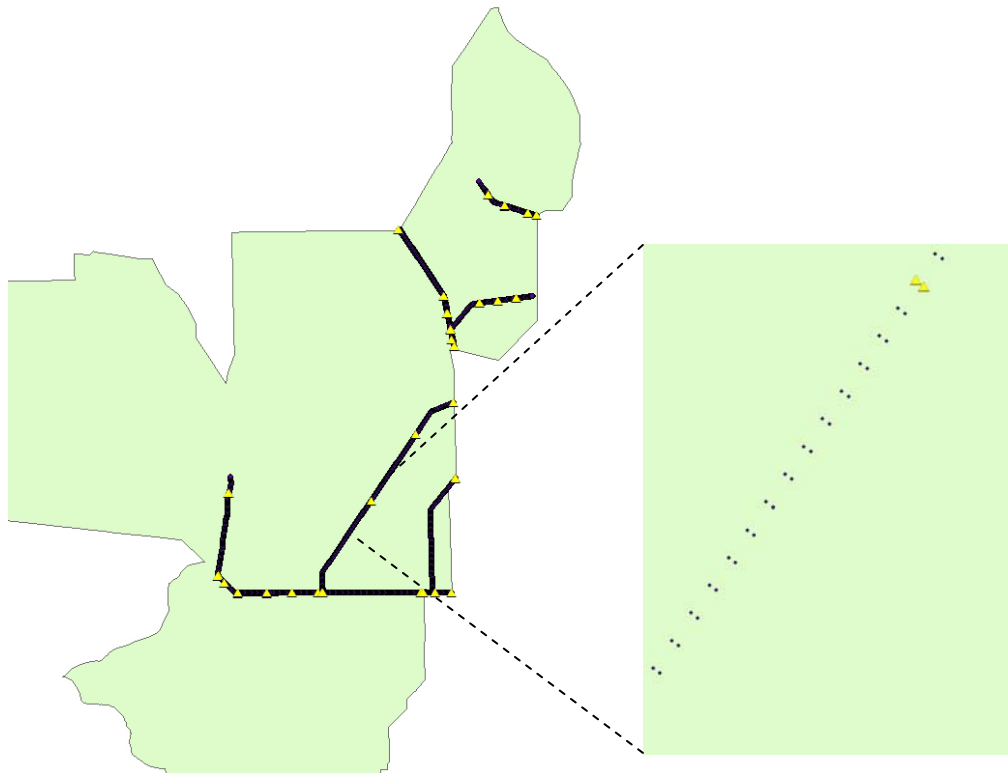


Figure 4. Levee and canal locations where boundary conditions were created for interpolation. The yellow triangles are the locations of water stage gages. The close-up illustrates linear interpolation of head and tail pseudo-stations every 200m along a levee.

Using Geostatistical Analyst in ArcGIS 9.x (Johnston et al. 2001, radial basis function interpolation with the multiquadric method was used to create a continuous mathematical representation of the water surface that was sampled further on a 400 x 400 m grid spacing to record the interpolated values. These results are combined with a digital elevation model (DEM) to obtain daily water depths (Figure 5). Details of EDEN grid, ground surface elevation sampling and modeling are in Jones and Price (2007a) and Jones and Price (2007b). The 400m x 400 m interpolated grid is stored in NetCDF format (Appendix B) which allows rapid retrieval of geo-coded time-series data and import into ArcGIS.

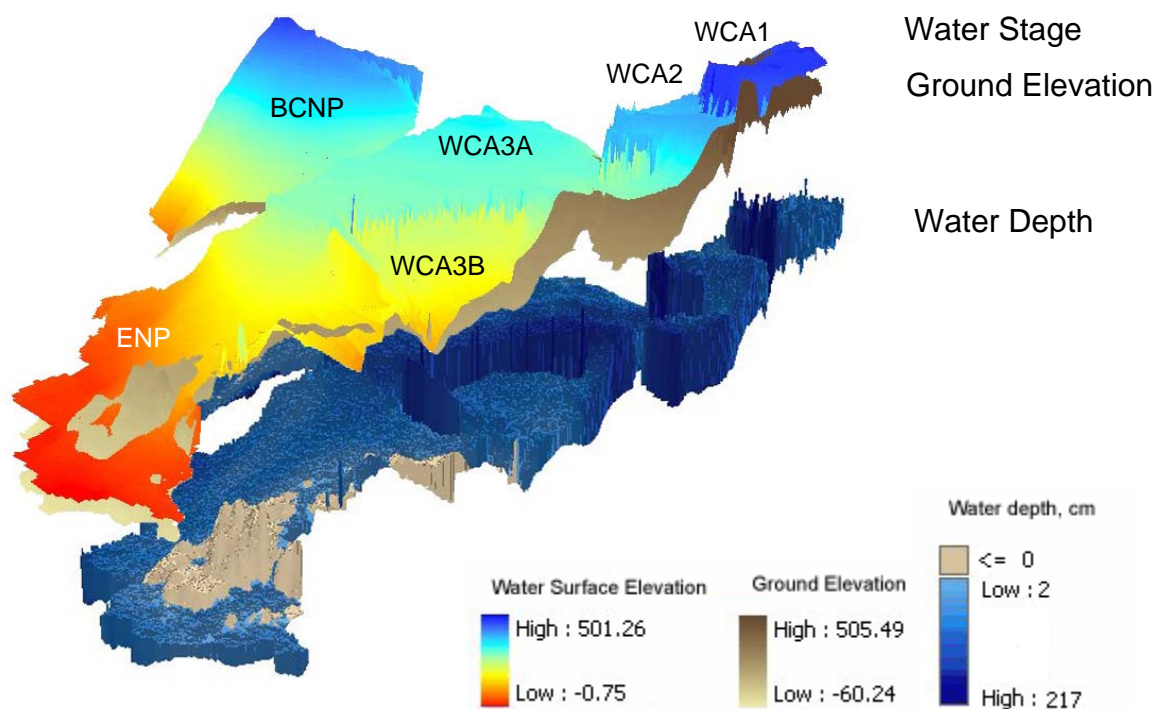


Figure 5. Water stage minus ground elevation produces an estimate of water depth. The tan area in Everglades National Park (ENP) is where ground surface is above the water surface. This example is for a sample day in November 2005. Vertical units are cm, NAVD 88.

Radial Basis Function Interpolation Method

The multiquadric method was first established by Hardy in 1968 and made public in 1971 (Hardy, 1971 1977). Later it was demonstrated mathematically that this method is a case of biharmonic analysis in an arbitrary number of dimensions (Dyn and Levin,

1980, 1983, Barnhill and Stead, 1984, Hardy and Nelson, 1986, Michelli, 1986, Foley, 1987, Madych and Nelson, 1990). The multiquadric equations are also continuously differentiable integrals. The method was tested on both “real world” data in geophysics, surveying and mapping, photogrammetry and remote sensing, digital terrain models and hydrology, as well as on mathematical surfaces. Franke (1982) gave a critical account and comparison of 29 interpolation methods tested on generated mathematical surfaces from sparse and scattered data. None of the methods investigated by Franke (1982) belonged to the kriging family. Hardy’s multiquadric method performed the best or the second best in Franke’s study: “In terms of fitting ability and visual smoothness, the most impressive method included in the tests is the “multiquadric” method, due to Hardy. ... The method ... yields consistently good results, often giving the most accurate results of all tested methods.” (Franke, 1982, pp. 191).

Radial Basis Function (RBF) is Referred to as an exact interpolation technique because the interpolated surface always passes exactly through the data points. RBF interpolations use a set of n radial basis functions, one for each location, while minimizing the total curvature of the surface (Johnston et al. 2001). Thus, the predictor is a linear combination of the radial basis function

$$Z(s_0) = \sum_{i=1}^n \omega_i \phi(d)$$

where $\phi(d)$ is a radial basis function with $d = \|s_i - s_0\|$ the Euclidian distance between the prediction location s_0 and each known data location s_i and ω_i the equation weights. In Figure 6 for three different locations, the RBF surface is illustrated in a different line type. For a set of coordinates of a predicted value location, the predictor will be formed by summing the weighted functions ϕ_1, ϕ_2, ϕ_3 for each known location. Weighting enforces the condition that when predicting a measured value, this value is predicted exactly (Johnston et al. 2001). One difference between a simple Inverse Distance Weighting (IDW) and RBF interpolation is that IDW will have no predicted values below or above the minimum or maximum measured values, respectively. RBF predicted values, however, could be outside the measured values interval.

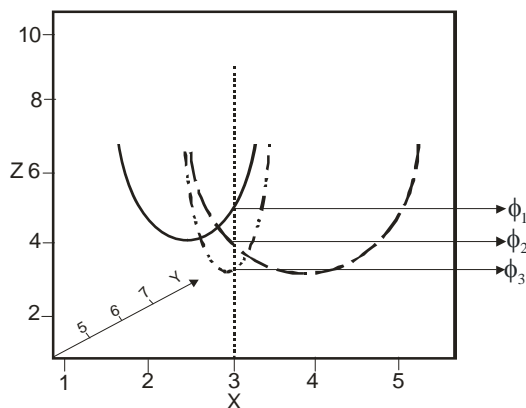


Figure 6. RBF prediction concept (modified after Johnston et al. 2001, p. 127)

$$Z(x, y) = w_1\phi_1 + w_2\phi_2 + w_3\phi_3, \text{ where } x = 3, y = 4$$

The radial basis function selected for this study uses the multiquadric function, defined as: $\phi(d) = (d^2 + r^2)^{1/2}$, where r is the smoothing or the shape parameter. If r is small, the resulting interpolated surface has minimal curvature forming a cone like basis function with the generated surface being very “tight” around the data points (Kansa and Carlson 1992; Golberg et al. 1996; Johnston et al. 2001). As r increases, the curvature of the function gradually flattens until the basis function is almost flat (Kansa and Carlson 1992; Golberg et al. 1996). There is much discussion about how to choose the shape parameter r , but no fool-proof method exists, only empirical formulas. The majority of the empirical formulas tie the parameter r to the scale of the problem at hand, the distribution of data, and their density (Hardy 1977; Gopfert 1977; Franke 1982; Golberg et al. 1996; Rippa 1999; and Ferreira et al. 2005). Others made the parameter r dependent only to the data points measured value z_i (Carlson and Foley, 1991) or used a variable parameter r instead of a constant one for large datasets (Kansa, 1990 a and b, Kansa and Carlson, 1992).

Comparison between Kriging and Multiquadric

Sirayanone (1988, cited in Hardy, 1990) proved that the multiquadric method of interpolation generates a statistically unbiased result without being a stochastic method by setting the condition that the sum of the weight coefficients equals one. Hardy (1988) and Hardy and Sirayanone (1989) have proved that multiquadric and kriging methods have almost equal accuracy in bivariate distributions, multiquadric having the advantage to be easily transformed for stereo-viewing of 3D bodies, and does not require data stationarity as kriging does. Similar results regarding the equivalency of kriging and multiquadric interpolation results have been reported by Myers (1994) and Borga and Vizzaccaro (1997). Syed et al. (2003) using rainfall data has demonstrated that multiquadric and kriging produce comparable results when variograms are developed using data from specific events, although kriging had inferior results when the variogram parameters were developed from monthly averages.

Modeling Parameters

In ArcGIS 9.x, the following parameters are selected:

- Input files are
 1. An extended data file for median water levels at each gage and each re-sampled point between canal gages
 2. An empty EDEN grid used as a template for final output grid has the following characteristics:
 - UTM, zone 17N, NAD 1983, units: meters
 - Cell size: 400 x 400 meters
 - Bounding rectangle: Top: 2952000.0m Bottom: 2790000.0m
Left: 463200.0m Right: 578000.0m

3. DEM at 400x400 m resolution matching the EDEN grid
 4. EDEN boundary polygon for clipping the modeled output to the study area. The current EDEN boundary is smaller than the EDEN grid, allowing for future expansion.
- Water stage modeled for each day with the Radial Basis Function in Geostatistical Analyst is selected with the following parameters:
 1. Kernel Functions: Multiquadric with a parameter = 16.77
 2. Neighbors to Include = 1
 3. Include at least = 1
 4. Shape type = 8 sectors
 5. Angle = 350
 6. Major semiaxis = 31000
 7. Minor semiaxis = 30000

Improving Accuracies

Cross-validation errors are saved for each daily water surface produced. Factors that could influence cross-validation absolute errors of predicted water levels include minimum distance between stations and absolute difference between the measured values of each station to their respective nearest station measured value. Additional gages were added to the EDEN network, as described below, to improve water stage interpolations. A report on cross-validation errors as a function of nearest station measured values has been submitted for publication. As new publications and information are released, they will be cited at <http://sofia.usgs.gov/eden>.

New Stations

In 2006, new 23 stations (EDEN stations) were established based on proximity analysis of 400 m resolution grid maps in which each cell represents distance from the center of the cell to its nearest real-time station. Figure 7a is based on the distance from each grid to original real-time stations. Figure 7b is based on the distance from each grid to all real-time stations including the ones converted to real-time (non-telemetered gages previously operated by Wiley Kitchens, USGS; and John Volin, Florida Atlantic University) and newly constructed EDEN stations. The gray scale indicates near (dark tone) to far (light tone) to the nearest station of each grid. Distances beyond 5,500 m were considered to be gaps in coverage based on neural network regressions by Paul Conrads, USGS (Unpublished) in WCA3 that generally demonstrated excellent predictions of water level at stations up to 6,000 m from an index station. Figure 7b illustrates that conversion of Kitchens and Volin stations to real-time and addition of EDEN stations filled out the major gaps appearing in Figure 7a and thus, is expected to improve overall accuracy of spatial prediction of water depth.

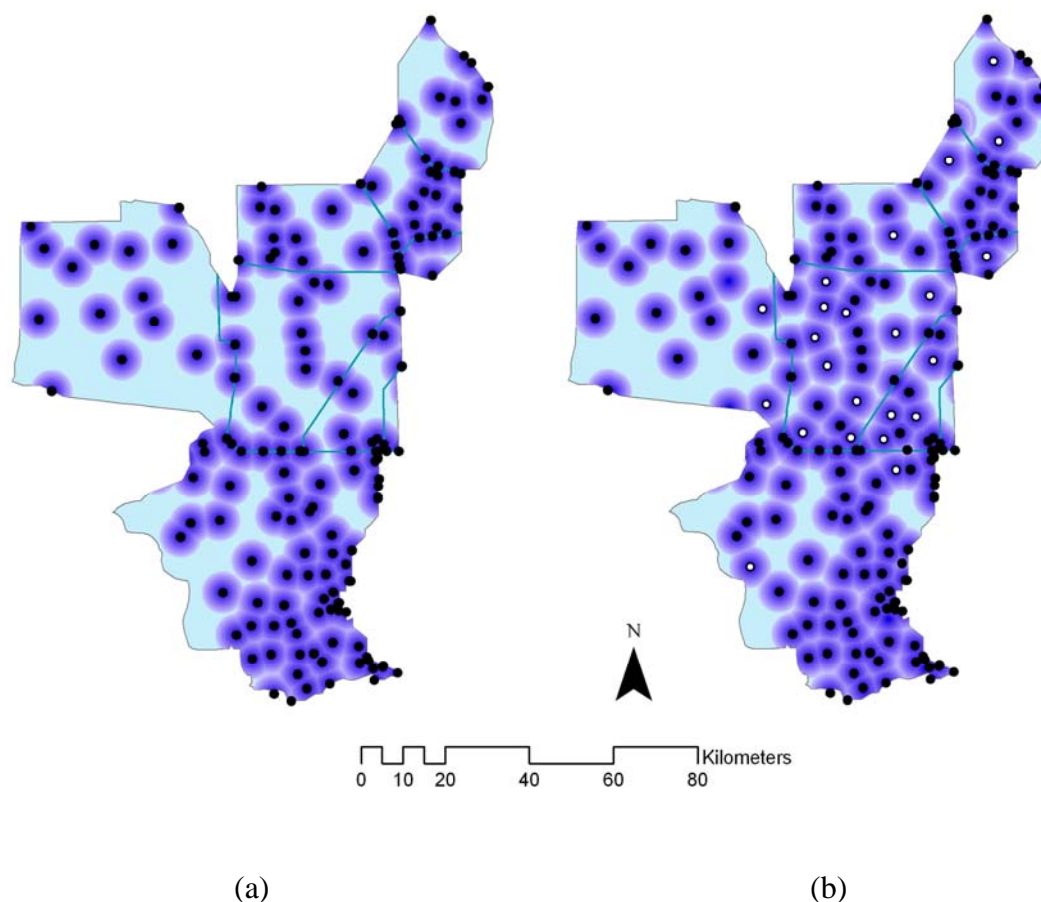


Figure 7. 400 m resolution maps based on distance from each grid to its nearest station before (a) and after (b) adding Kitchen, Volin, and new EDEN stations. The color gradient indicates near (dark tone) to far (light tone). New stations in (b) are indicated with white centers.

Hindcasting New Water Stage Gaging Stations

Daily gage data were compiled for all the stations in the EDEN network for the period beginning January 2000 to current, except for the new stations. The new stations are recording and available for improving water stage interpolation since July 2006. Neural network analysis has been used to provide an estimate of water stage at the new gage sites over the historic record (January 2000 to July 2006). Neural network analysis used static variables including percent prairie, percent sawgrass, percent upland, latitude, and longitude and dynamic water stage variables from existing gages surrounding the new location to predict stage at the new location. Details are provided in Conrads (2006).

This estimate allows us to treat these locations as gaged sites over the entire record and improves interpolation of water stage surfaces for the historic record when the new gages were not actually established and collecting data.

The radial basis function interpolation is applied daily to daily median gage data in NAVD 88 composed of observed gage data, linearly interpolated “pseudo-gage data” along canals, and, prior to July 2006, hindcast gage data where new gages have since been established. Examples of spatially continuous interpolated water stage are shown in Figure 8.

Water depth is estimated when ground elevation from the EDEN DEM is subtracted from water stage as shown in Figure 9. Field observations of water depth have been compiled from numerous independent investigators and are continuing to be compiled. These data provide a comparison and validation of EDEN water depth results. Differences between EDEN modeled water depths and observed depths may be the result of (1) errors in the modeled water surface, (2) errors in the DEM, or (3) field measurement errors and different protocols among investigators. Particularly where differences are systematic over time and/or space, it may be possible to develop explanations that aid in producing improved depth estimations in the future. Water depth validation of EDEN interpolations prior to the addition of the new stations have been submitted for publication. Work on water depth estimation and comparisons to field observations is continuing and as new publications and information are released, they will be cited at <http://sofia.usgs.gov/eden>.

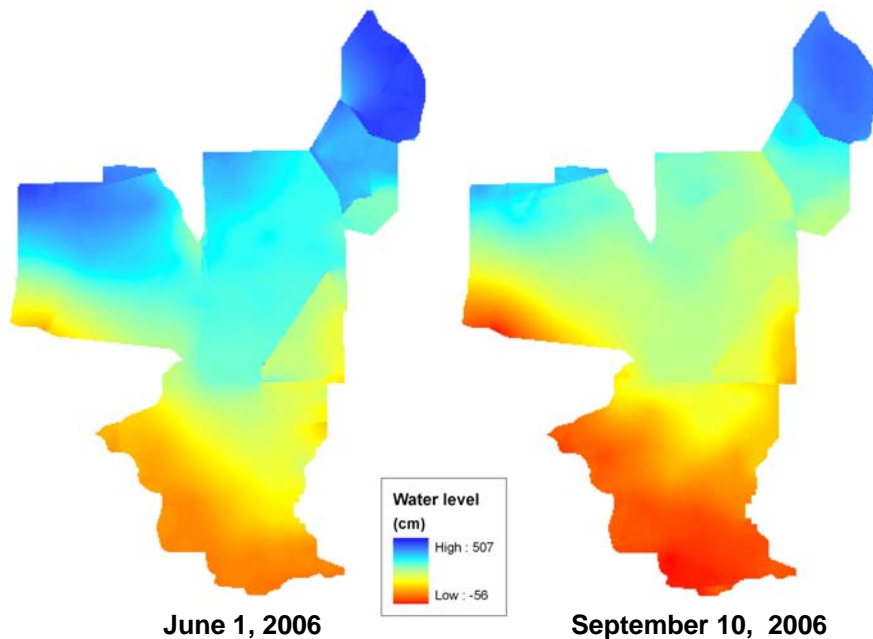


Figure 8. Water stage example from a wet season (left) and dry season (right) day.

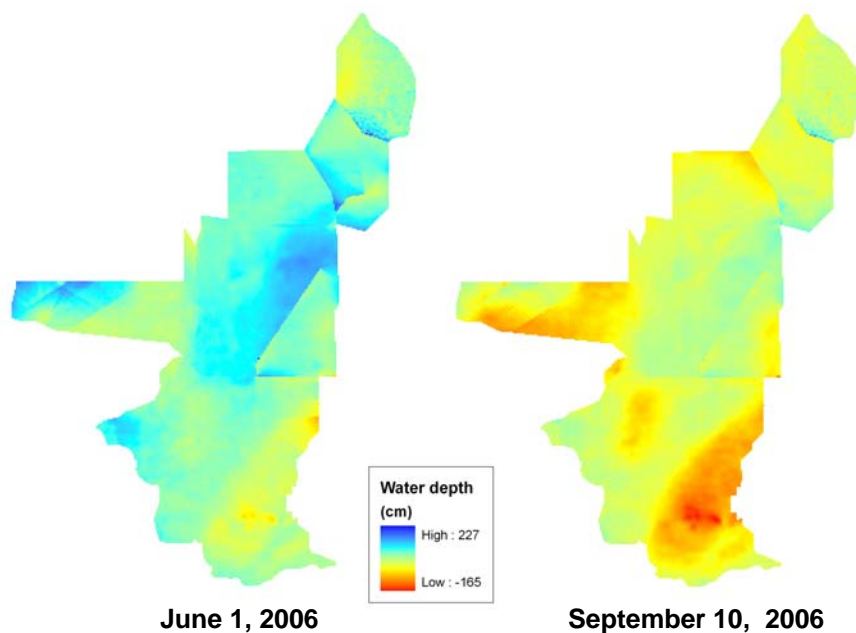


Figure 9. Water depth example from a wet season (left) and dry season (right) day.

Confidence Index Maps

A spatial confidence index map is created for each day in which a water stage is surfaced. The index gives a general indication of how much confidence can be assigned to the accuracy of any specific location on the surface. The confidence index is a geometric mean of three input layers: (1) distance from water stage gages, (2) distance from canals, and (3) cross-validation results for the generated surface. For distance from water stage gages, values range linearly from 1 (optimal) at the gage to 0 (no confidence) at 10km. Distance from canals is optimal when locations are at least 2km from canals and approaches 0 as locations get nearer to a canal. Cross validation error computed by the radial basis function model for each station that had data on that day is applied to all the area closest to that station relative to all other stations (Thiessen polygon). The error represents the difference between measured and predicted water level for a station; the lower the error, the higher the confidence. Figure 10 illustrates improved confidence in the surfaced stage data layer when the new stations are included in the interpolation. Appendix C details the creation of confidence index maps in ArcGIS.

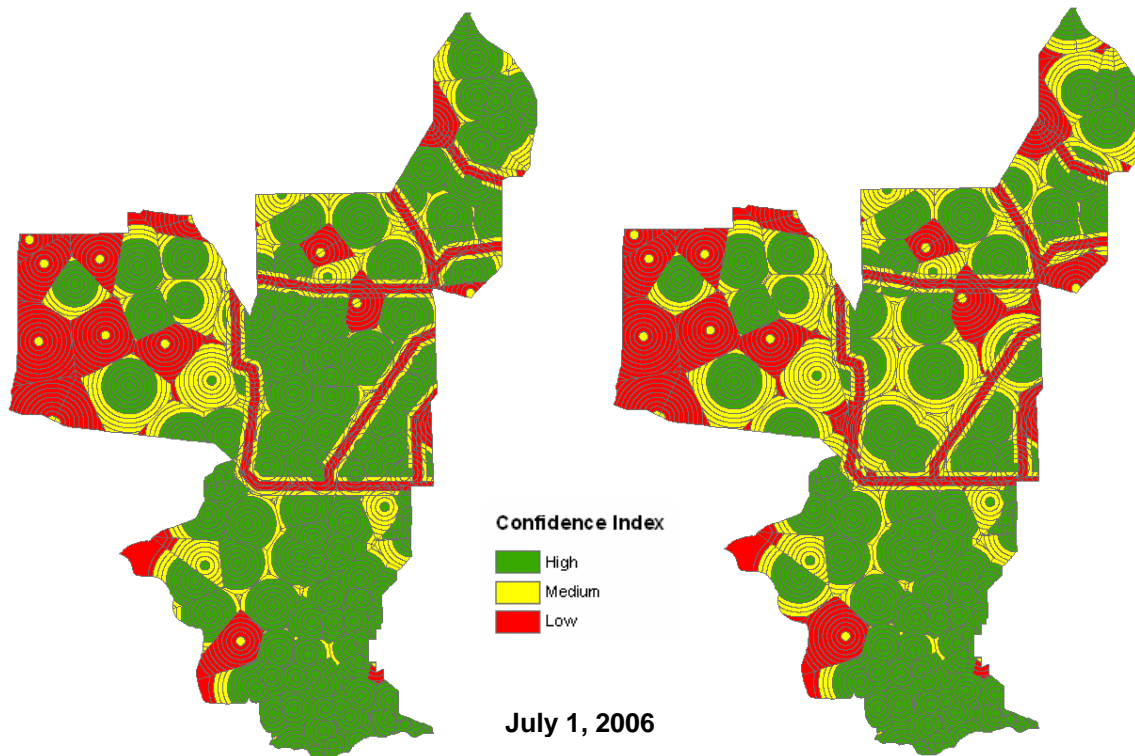


Figure 10. Confidence index maps for water stage surface developed with (left) and without (right) data at the new EDEN gaging stations.

Discussion

Two hundred and forty water level recorders provide the information for EDEN interpolations of daily water stage that provide spatially-explicit hydrologic predications necessary for modeling floral and faunal habitat suitability and distributions across the entire Everglades. These models are critical for evaluations of alternative Everglades restoration plans and monitoring of the habitat impacts of surface hydrologic dynamics. The interpolated surface covers the freshwater marsh and wetland forests of the Everglades system, however it does not attempt to predict surface water level in the coastal areas where stage is tide and wind-driven. It is anticipated that the SICS/TIME model (Wang et al. 2007) will be integrated with EDEN to provide stage surfaces along the coast in the future.

Sources of prediction errors may include model insufficiency, scale issues, density of stage gages, and proximity to abrupt changes in the surface (levees and canals). When independent observations of water stage or water depth are used for validation, differences in measurements methodologies between gage and field measurements can

produce significant “apparent errors,” particularly for water depth measurements in the Everglades marsh communities. In the coming year, the EDEN project will be working with independent observers to increase our understanding of how these potential errors are partitioned.

The RBF method forces the interpolated continuous surface to pass exactly through observation points and therefore, the surface at gage locations precisely matches observations. The continuous surface is sampled to the 400 m grid by selecting the center elevation value as the value for the grid. If the location of interest is toward the edge of a grid, then the error introduced by gridding depends on the slope of the surface within the grid. Our observation is that the difference is usually within 1 cm, however the difference is still to be documented. The RBF method mimics the smooth water surface between stations and it is our expectation that it is an accurate reflection of the real water surface. Confidence in the modeled surfaces has not been fully explored however, because of the lack of spatially independent water elevation data to be used for validation. Additional stage observations are becoming available however, particularly from studies by Dr. John Volin (Florida Atlantic University) in WCA3. Quantitative assessments of stage, slope of the water surface and water depth are possible and proceeding because of cooperative data-sharing by many Everglades researchers.

Scale is likely to be more of an issue in comparing our 400 m resolution predictions of water depth and field measurements (point measurements). Water surface typically varies gradually and smoothly and can usually be considered flat within a 400m grid. Ground surface, however, - and, therefore, water depth- is uneven and can easily change 20cm as an observer moves from slough to emergent grass communities within the same grid cell. Since accuracy of hydrologic models is scale dependent (Wolock and Price 1994), selecting the appropriate spatial scale is important. Obeysekera and Rutchey (1997) examined effects of varied scale on loss of information in landscape modeling in the Everglades. Their study indicated that the area-perimeter relationship rapidly changes beyond the 100 m scale and important features nearly disappear beyond the 700 m scale. Although model scale as fine as 100 m or less may be optimal, such fine scale modeling of the entire greater Everglades is prohibitive. Proposed research to address this issue includes finer scale analysis of water depths stratified by vegetation within hydrologically similar clusters of smaller areas.

An additional source of errors is that many of the recording gages “bottom-out” when water recedes below ground or below the bottom of the recording equipment at the gage. The result is a false reading of water stage at the surface when it should be lower and pulls the interpolated water surface up around that gage. EDEN is negotiating installation of ground water level recorders associated with the gaging stations to solve this problem at some of the more critical stations.

Getting surfaced data into the hands of the user is also critical to the success of EDEN as a resource for restoration. Tools for easy access to EDEN interpolated products have been and are being developed, including Web-based and PC-based interactive retrieval of data subsets over user-specified time periods, a utility for extracting

interpolated data points at specific x,y locations and a profiling tool. Metadata describing the spatial referencing, creation date, and interpolation version of the surfaced datasets are embedded in the data files and daily cross-validation results are available for each water surface. As new data and new tools are made available, they will be posted to <http://sofia.usgs.gov/eden> .

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Appendix A: Listing of EDEN water stage gaging stations

EDEN water stage stations are listed below in two tables, separated by marsh gages and canal gages. Marsh gages include marsh, marsh structure and river gages. Canal gages include canal and canal structure. Canal and marsh indicate stations located in uncontrolled regions, canal structure indicates a station located within a canal at a structure, usually with an associated station on the other side of the structure, marsh structure indicates a station located in the marsh at a structure, usually with an associated station on the other side of the structure. In both cases, the associated station does not have to be of the same type (canal or marsh).

Geographic coordinates (Latitude, Longitude) are in NAD83 datum. UTM coordinates are zone 17N, NAD83, meters. EDEN-funded water level gaging stations are highlighted. Additional metadata for each station is provided at <http://sofia.usgs.gov/eden>.

Table A1. Marsh Stations sorted by location. (Note: Tidal gages in the Gulf of Mexico basin were not used in the surface water interpolation for the freshwater Everglades)

Station Name	Type of Station	Operating Agency	Latitude	Longitude	UTM Easting	UTM Northing	Real Time Data Daily
Big Cypress National Preserve							
BCA1	Marsh	BCNP	26°14'33"	-81°19'14"	467985.6	2902579.2	Yes
BCA10	Marsh	BCNP	25°42'49"	-81°01'19"	497798.55	2843968.9	Yes
BCA11	Marsh	BCNP	25°47'21"	-81°06'00"	489974.43	2852339.5	Yes
BCA12	Marsh	BCNP	26°11'29"	-81°05'12"	491340.7	2896882.1	Yes
BCA13	Marsh	BCNP	26°05'35"	-81°03'13"	494638.96	2885990.3	Yes
BCA14	Marsh	BCNP	26°02'40"	-81°18'00"	469987.92	2880640.3	Yes
BCA15	Marsh	SFWMD	26°02'23"	-81°01'36"	497325.26	2880093.3	Yes
BCA16	Marsh	SFWMD	26°03'24"	-81°09'20"	484432.6	2881978.7	Yes
BCA17	Marsh	SFWMD	26°12'18"	-81°10'05"	483203.49	2898407	Yes
BCA18	Marsh	SFWMD	26°12'24"	-80°58'59"	501686.06	2898580.7	Yes
BCA19	Marsh	SFWMD	25°47'35"	-81°12'08"	479719.22	2852793.3	Yes
BCA2	Marsh	BCNP	26°11'46"	-81°17'19"	471164.52	2897434.3	Yes
BCA20	Marsh	SFWMD	25°42'23"	-80°56'05"	506542.12	2843182.1	Yes
BCA3	Marsh	BCNP	26°09'24"	-81°13'18"	477845.59	2893052.8	Yes
BCA4	Marsh	BCNP	25°57'26"	-81°06'14"	489599.28	2870950.6	Yes
BCA5	Marsh	BCNP	25°58'06"	-80°55'35"	507368.8	2872179	Yes
BCA6	Marsh	BCNP	25°51'07"	-80°58'52"	501892.72	2859287.9	Yes
BCA7	Marsh	BCNP	25°53'12"	-81°15'44"	473732.23	2863159.2	Yes
BCA8	Marsh	BCNP	25°53'25"	-81°16'13"	472926.09	2863560.8	Yes
BCA9	Marsh	BCNP	25°46'42"	-80°54'44"	508801.02	2851139	Yes
EDEN_1	Marsh	USGS	25°51'38"	-80°53'42"	510514.97	2860236.4	Yes
EDEN_6	Marsh	USGS	26°03'55"	-80°54'14"	509613.26	2882916.5	Yes
L28_GAP	Marsh	SFWMD	26°07'28"	-80°59'00"	501659.44	2889475.3	Yes
LOOP1_H	Marsh structure	SFWMD	25°45'41"	-80°54'28"	509238.96	2849262.5	Yes
LOOP1_T	Marsh structure	SFWMD	25°45'40"	-80°54'28"	509241.26	2849228.3	Yes
LOOP2_H	Marsh structure	SFWMD	25°44'48"	-80°57'14"	504624.73	2847630.7	Yes
LOOP2_T	Marsh structure	SFWMD	25°44'48"	-80°57'15"	504601.42	2847616.9	Yes
S344_T	Marsh structure	SFWMD	25°55'08"	-80°50'12"	516353.55	2866724.2	Yes

Everglades National Park

A13	Marsh	ENP	25°29'50"	-80°42'45"	528887.43	2820049.8	Yes
C111_wetland_east_of_F							
IU_LTER_TSPH5	Marsh	USGS	25°17'40"	-80°31'12"	548320.95	2797638.3	Yes
CP	Marsh	ENP	25°13'39"	-80°42'14"	529818.81	2790185.1	Yes
CR2	Marsh	ENP	25°29'55"	-80°37'18"	538016.06	2820226.4	Yes
CR3	Marsh	ENP	25°29'48"	-80°39'46"	533884.83	2820000	Yes
CT27R	Marsh	ENP	25°18'03"	-80°29'19"	551472.28	2798370.4	Yes
CT50R	Marsh	ENP	25°18'46"	-80°31'15"	548223.82	2799681.1	Yes
CV5NR	Marsh	ENP	25°18'08"	-80°29'15"	551583.54	2798524.7	Yes
CY2	Marsh	ENP	25°19'39"	-80°40'58"	531919.14	2801262.9	Yes
CY3	Marsh	ENP	25°19'40"	-80°45'02"	525097.66	2801279.3	Yes
DO1	Marsh	ENP	25°22'19"	-80°41'27"	531097.06	2806182.4	Yes
DO2	Marsh	ENP	25°23'18"	-80°44'39"	525727.88	2807985.9	Yes
E112	Marsh	ENP	25°25'26"	-80°36'35"	539240.68	2811955.6	Yes
E146	Marsh	ENP	25°15'13"	-80°39'59"	533588.89	2793085.2	Yes
EDEN_3	Marsh	USGS	25°30'44"	-80°55'59"	506727.07	2821669	Yes
EPSW	Marsh	ENP	25°16'17"	-80°30'29"	549526.79	2795102.7	Yes
EVER4	Marsh	USGS	25°20'37"	-80°32'42"	545779.69	2803086.9	Yes
EVER6	Marsh	ENP	25°17'49"	-80°30'41"	549180.86	2797931.3	Yes
EVER7	Marsh	ENP	25°18'31"	-80°32'32"	546072.44	2799212.2	Yes
EVER8	Marsh	ENP	25°20'42"	-80°28'42"	552487.9	2803265.1	Yes
L31W	Marsh	ENP	25°26'13"	-80°35'23"	541247.55	2813407.3	Yes
MET-1	Marsh	USGS	25°43'13"	-80°35'18"	541300.2	2844777.7	Yes
NCL	Marsh	ENP	25°14'33"	-80°44'40"	525730.64	2791837.7	Yes
NE1	Marsh	USGS	25°41'31"	-80°38'04"	536672.92	2841631.5	Yes
NE2	Marsh	USGS	25°43'16"	-80°33'14"	544745.08	2844886.2	Yes
NE4	Marsh	USGS	25°38'29"	-80°39'10"	534848.01	2836028.3	Yes
NE5	Marsh	USGS	25°37'54"	-80°39'35"	534153.67	2834949.9	Yes
NESRS3	Marsh	SFWMD	25°44'26"	-80°30'16"	549697.14	2847057.1	No
NP201	Marsh	ENP	25°43'00"	-80°43'10"	528138.14	2844348.3	Yes
NP202	Marsh	ENP	25°39'43"	-80°42'31"	529238.28	2838291	Yes
NP203	Marsh	ENP	25°37'22"	-80°44'19"	526235.86	2833947.6	Yes
NP205	Marsh	ENP	25°41'19"	-80°50'52"	515267.35	2841220.6	Yes
NP206	Marsh	ENP	25°32'39"	-80°40'19"	532950.59	2825257.5	Yes
NP44	Marsh	ENP	25°26'00"	-80°43'13"	528120.54	2812973.6	Yes
NP46	Marsh	ENP	25°19'06"	-80°47'45"	520542.31	2800225.8	Yes
NP62	Marsh	ENP	25°26'18"	-80°46'58"	521834.87	2813515.6	Yes
NP67	Marsh	ENP	25°19'46"	-80°39'01"	535189.52	2801486.4	Yes
NP72	Marsh	ENP	25°23'41"	-80°42'11"	529861.83	2808701.8	Yes
NTS1	Marsh	ENP	25°26'12"	-80°35'34"	540940.39	2813375.6	Yes
NTS10	Marsh	ENP	25°27'37"	-80°36'18"	539703.67	2815986.5	Yes
NTS14	Marsh	ENP	25°24'59"	-80°38'19"	536337.73	2811117	Yes
NTS18	Marsh	ENP	25°29'02"	-80°33'59"	543576.93	2818613.1	Yes
OL	Marsh	ENP	25°15'49"	-80°36'47"	538956.66	2794206.9	Yes
OT	Marsh	ENP	25°34'43"	-80°57'52"	503563.89	2829031.6	Yes
P33	Marsh	ENP	25°36'50"	-80°42'08"	529891.45	2832971	Yes
P34	Marsh	ENP	25°36'27"	-80°56'27"	505933.85	2832231.4	Yes
P35	Marsh	ENP	25°27'35"	-80°51'52"	513620.73	2815873.2	Yes
P36	Marsh	ENP	25°31'38"	-80°47'44"	520534.99	2823356.4	Yes
P37	Marsh	ENP	25°17'03"	-80°41'18"	531371.13	2796463.3	Yes
P38	Marsh	ENP	25°22'10"	-80°50'00"	516760.87	2805880.2	Yes
R127	Marsh	ENP	25°21'11"	-80°36'22"	539626.91	2804113.2	Yes
R3110	Marsh	ENP	25°26'46"	-80°37'34"	537585.66	2814411.6	Yes
RG1	Marsh	ENP	25°34'53"	-80°36'28"	539384.9	2829396.8	Yes
RG2	Marsh	ENP	25°32'33"	-80°36'21"	539592.96	2825091	Yes
SP	Marsh	ENP	25°23'19"	-80°47'50"	520390.78	2808007.5	Yes
Taylor_Slough_wetland_							
at_E146	Marsh	USGS	25°14'57"	-80°39'58"	533624.49	2792579.9	Yes
TMC	Marsh	ENP	25°36'50"	-80°52'20"	512822.47	2832943.7	Yes
TS2	Marsh	ENP	25°24'00"	-80°36'24"	539555.74	2809311.3	Yes

TSH	Marsh	ENP	25°18'39"	-80°37'50"	537180.09	2799430.9	Yes
S12A_T	Marsh structure	USGS	25°45'41"	-80°49'16"	517941.2	2849281.2	Yes
S12B_T	Marsh structure	USGS	25°45'42"	-80°46'10"	523113.3	2849299.6	Yes
S12C_T	Marsh structure	USGS	25°45'42"	-80°43'37"	527381.63	2849310.3	Yes
S12D_T	Marsh structure	USGS	25°45'42"	-80°40'55"	531907.94	2849325.5	Yes
S332B_T	Marsh structure	SFWMD	25°32'58"	-80°33'38"	544138.76	2825874.6	Yes
S332_T	Marsh structure	SFWMD	25°25'19"	-80°35'26"	541180	2811722.3	Yes
Water Conservation Area 1							
NORTH_CA1	Marsh	USGS	26°35'38"	-80°21'13"	564356.19	2941626.1	Yes
SITE_7	Marsh	USGS	26°31'11"	-80°20'49"	565061.88	2933415.4	Yes
SITE_8C	Marsh	USGS	26°30'01"	-80°13'21"	577474.8	2931309.2	Yes
SITE_8T	Marsh	USGS	26°29'59"	-80°14'05"	576266.93	2931241.7	Yes
SITE_9	Marsh	USGS	26°27'51"	-80°17'49"	570077.53	2927288.8	Yes
SOUTH_CA1	Marsh	USGS	26°25'29"	-80°20'26"	565752.41	2922897.3	Yes
WCA1ME	Marsh	SFWMD	26°30'39"	-80°18'36"	568748.31	2932450.2	Yes
Water Conservation Area 2A							
2A300	Marsh	SFWMD	26°14'47"	-80°24'29"	559111.67	2903114.4	No
EDEN_11	Marsh	USGS	26°22'35"	-80°27'19"	553893.8	2918188.1	Yes
SITE_17	Marsh	USGS	26°17'12"	-80°24'39"	558813.97	2907573.8	Yes
SITE_19	Marsh	USGS	26°16'56"	-80°18'22"	569272.04	2907133.4	Yes
WCA2E1	Marsh	SFWMD	26°21'07"	-80°21'10"	564574.02	2914831	No
WCA2E4	Marsh	SFWMD	26°18'35"	-80°21'23"	564236.97	2910153.1	No
WCA2F1	Marsh	SFWMD	26°21'36"	-80°22'11"	562878.89	2915714.7	No
WCA2F4	Marsh	SFWMD	26°19'02"	-80°23'05"	561404.79	2910969.9	No
WCA2RT	Marsh	SFWMD	26°19'48"	-80°30'35"	548922.85	2912331.7	No
WCA2U1	Marsh	SFWMD	26°14'29"	-80°21'21"	564330.06	2902585.6	No
WCA2U3	Marsh	SFWMD	26°17'17"	-80°24'39"	558813.27	2907727.6	No
S10A_T	Marsh structure	USGS	26°21'33"	-80°18'46"	568563.45	2915633.1	Yes
S10C_T	Marsh structure	USGS	26°22'16"	-80°21'09"	564583.86	2916948	Yes
S10D_T	Marsh structure	USGS	26°23'18"	-80°22'55"	561635.81	2918827.9	Yes
S11A_H	Marsh structure	USGS	26°10'37"	-80°26'54"	555115.46	2895405.3	Yes
S11B_H	Marsh structure	USGS	26°12'09"	-80°27'14"	554557.92	2898235.2	Yes
S11C_H	Marsh structure	USGS	26°13'47"	-80°27'35"	553950.86	2901225.2	Yes
S144_H	Marsh structure	SFWMD	26°13'06"	-80°23'52"	560158.68	2900008.9	No
S145_H	Marsh structure	SFWMD	26°13'19"	-80°21'57"	563348.91	2900416.9	No
S146_H	Marsh structure	SFWMD	26°13'32"	-80°20'01"	566576.24	2900838.9	No
Water Conservation Area 2B							
EDEN_13	Marsh	USGS	26°10'35"	-80°22'17"	562816.46	2895370	Yes
SITE_99	Marsh	USGS	26°08'14"	-80°22'01"	563276.53	2891044	Yes
S141_H	Marsh structure	SFWMD	26°09'02"	-80°26'32"	555755.44	2892486.9	No
S144_T	Marsh structure	SFWMD	26°13'05"	-80°23'52"	560164.6	2899975.5	No
S145_T	Marsh structure	SFWMD	26°13'18"	-80°21'57"	563352.07	2900385.7	No
S146_T	Marsh structure	SFWMD	26°13'31"	-80°20'00"	566581.41	2900799.4	No
Water Conservation Area 3A							
3A10	Marsh	SFWMD	26°16'46"	-80°44'23"	525980.05	2906666.3	No
3A11	Marsh	SFWMD	26°13'06"	-80°44'37"	525605.14	2899897.8	No
3A12	Marsh	SFWMD	26°10'09"	-80°40'32"	532417.15	2894468.1	No
3A-5	Marsh	USGS	26°03'24"	-80°42'19"	529481.03	2881992.6	Yes
3A9	Marsh	SFWMD	26°07'23"	-80°38'51"	535234.78	2889368.9	No
3AN1W1	Marsh	SFWMD	26°11'17"	-80°44'24"	525972.58	2896545.5	Yes
3ANE	Marsh	SFWMD	26°16'44"	-80°36'17"	539459.07	2906638.9	Yes
3ANW	Marsh	SFWMD	26°17'09"	-80°46'32"	522401.12	2907367.1	Yes
3AS	Marsh	SFWMD	26°05'01"	-80°41'03"	531579.54	2884991.4	Yes
3AS3W1	Marsh	SFWMD	25°51'27"	-80°46'15"	522955.75	2859933.8	Yes
3ASW	Marsh	SFWMD	25°59'24"	-80°50'09"	516424.38	2874597	Yes
EDEN_12	Marsh	USGS	26°00'42"	-80°35'17"	541222.59	2877040.8	Yes
EDEN_14	Marsh	USGS	26°04'10"	-80°45'27"	524254.59	2883397	Yes
EDEN_4	Marsh	USGS	26°05'36"	-80°30'25"	549305.17	2886113.3	Yes
EDEN_5	Marsh	USGS	26°07'25"	-80°45'10"	524715.52	2889396.6	Yes
EDEN_8	Marsh	USGS	25°52'00"	-80°40'50"	532005.36	2860957.1	Yes
EDEN_9	Marsh	USGS	26°13'19"	-80°35'32"	540732.67	2900327.2	Yes

SITE_62	Marsh	USGS	26°10'29"	-80°45'04"	524865.17	2895066.7	Yes
SITE_63	Marsh	USGS	26°11'20"	-80°31'51"	546872.5	2896696.4	Yes
SITE_64	Marsh	USGS	25°58'32"	-80°40'09"	533109.96	2873028.9	Yes
SITE_65	Marsh	USGS	25°48'53"	-80°43'11"	528087.23	2855206.6	Yes
W11	Marsh	USGS	25°56'34"	-80°45'00"	525031.57	2869370.8	Yes
W14	Marsh	USGS	25°56'14"	-80°40'06"	533210.16	2868773.7	Yes
W15	Marsh	USGS	26°00'51"	-80°40'40"	532243.48	2877292.5	Yes
W18	Marsh	USGS	26°00'07"	-80°46'44"	522127.95	2875917.9	Yes
W2	Marsh	USGS	25°47'59"	-80°48'32"	519158.29	2853518.6	Yes
W5	Marsh	USGS	25°47'21"	-80°41'43"	530550.21	2852371.1	Yes
S11A_T	Marsh structure	USGS	26°10'37"	-80°26'57"	555030.78	2895390.9	Yes
S11B_T	Marsh structure	USGS	26°12'09"	-80°27'18"	554456.55	2898221.3	Yes
S11C_T	Marsh structure	USGS	26°13'46"	-80°27'39"	553853.05	2901210.4	Yes
S142_T	Marsh structure	SFWMD	26°09'36"	-80°26'47"	555326.93	2893522.7	No
S150_T	Marsh structure	SFWMD	26°20'05"	-80°32'22"	545964.12	2912820.6	Yes
S150_T	Marsh structure	USGS	26°20'05"	-80°32'22"	545964.12	2912820.6	No
S343A_H	Marsh structure	SFWMD	25°47'21"	-80°51'19"	514522.22	2852358.7	Yes
S343B_H	Marsh structure	SFWMD	25°46'42"	-80°50'38"	515652.05	2851135.3	Yes
S344_H	Marsh structure	SFWMD	25°55'08"	-80°50'11"	516395.18	2866714.4	Yes
Water Conservation Area 3B							
3BS1W1	Marsh	SFWMD	25°46'50"	-80°30'40"	549012.05	2851484.1	Yes
3B-SE	Marsh	SFWMD	25°47'17"	-80°29'58"	550178.69	2852319	No
EDEN_7	Marsh	USGS	25°57'08"	-80°29'55"	550198.51	2870488.9	Yes
EDEN_10	Marsh	USGS	25°47'07"	-80°37'02"	538377.06	2851960.8	Yes
SITE_69	Marsh	USGS	25°54'24"	-80°35'20"	541208.91	2865450.1	Yes
SITE_71	Marsh	USGS	25°53'05"	-80°33'24"	544405.47	2863003.3	Yes
SITE_76	Marsh	USGS	26°00'28"	-80°28'57"	551781.68	2876657.8	Yes
SRS1	Marsh	USGS	25°47'55"	-80°34'42"	542265.46	2853460.3	Yes
TI-8	Marsh	USGS	25°49'57"	-80°32'28"	545989.77	2857214.7	Yes
TI-9	Marsh	USGS	25°50'14"	-80°35'58"	540141.95	2857718.6	Yes
S9A_T	Marsh structure	SFWMD	26°03'41"	-80°26'38"	555630.46	2882614.6	Yes
Florida Bay (Tidal Rivers)							
Joe_Bay_2E	River	USGS	25°13'55"	-80°31'28"	547898.05	2790715.8	Yes
McCormick_Creek_at_mouth	River	USGS	25°10'04"	-80°43'54"	527034.02	2783566.3	Yes
Mud_Creek_at_mouth	River	USGS	25°12'12"	-80°35'00"	541970.27	2787541.3	Yes
Stillwater_Creek	River	USGS	25°13'42"	-80°29'11"	551726.65	2790343.3	Yes
Upstream_Taylor_River	River	USGS	25°12'42"	-80°38'52"	535475.28	2788445.5	Yes
Taylor_River_at_mouth	River	USGS	25°11'28"	-80°38'20"	536376.84	2786171.8	Yes
Trouth_Creek_at_mouth	River	USGS	25°12'54"	-80°32'00"	547003.17	2788849.7	Yes
West_Highway_Creek	River	USGS	25°14'34"	-80°26'49"	555693.23	2791958.5	Yes
Gulf of Mexico (Tidal Rivers)							
Bottle_Creek_at_Rookery_Branch	River	USGS	25°28'06"	-80°51'15"	514652.96	2816827.8	Yes
Broad_River_near_the_Cutoff	River	USGS	25°30'06"	-81°04'36"	492287.91	2820513.2	Yes
Upstream_Broad_River	River	USGS	25°30'04.7"	-80°55'56"	506811.43	2820460.2	Yes
Chatham_River_near_the_Watson_Place	River	USGS	25°42'34"	-81°14'58"	474967.37	2843542.6	Yes
Harney_River	River	USGS	25°25'52.4"	-81°05'08.3"	491388.61	2812700.5	Yes
Lopez_River_Near_Lopez_Campsite	River	USGS	25°47'30"	-81°17'58"	469971.82	2852658.1	Yes
Lostmans_River_below_Second_Bay	River	USGS	25°33'21"	-81°09'52"	483473.78	2826506.9	Yes
Upstream_Lostmans_River	River	USGS	25°33'57"	-80°59'41"	500530.11	2827604.1	Yes
New_River_at_Sunday_Bay	River	USGS	25°47'52"	-81°15'19"	474401.14	2853325.5	Yes
North_River_Upstream_of_Cutoff	River	USGS	25°20'19"	-80°54'47"	508742.28	2802458.4	Yes
Upstream_North_River	River	USGS	25°21'29"	-80°54'00"	510026	2804598	Yes
Shark_River_Below_Gu	River	USGS	25°22'31"	-81°02'12"	496303.9	2806516.3	Yes

nboat_Island								
Turner_River_nr_Chokol								
oskee_Island	River	USGS	25°49'44"	-81°20'29"	465777.31	2856790.2	Yes	

Table A2. Canal Stations sorted by location.

Station Name	Type of Station	Operating Agency	Latitude	Longitude	UTM Easting	UTM Northing	Real Time Data Daily
C111 Canal							
S18C_T	Canal structure	USGS	25°19'15"	-80°31'30"	547801.27	2800571.6	Yes
L28 Canal							
L28S1	Canal	SFWMD	26°05'38"	-80°50'34"	515715.51	2886100.8	Yes
L28S2	Canal	SFWMD	26°05'38"	-80°50'05"	516521.07	2886101.8	Yes
S140_H	Canal structure	SFWMD	26°10'18"	-80°49'40"	517207.4	2894700	Yes
S343A_T	Canal structure	SFWMD	25°47'20"	-80°51'20"	514478.46	2852324.3	Yes
S343B_T	Canal structure	SFWMD	25°46'41"	-80°50'39"	515620.35	2851105	Yes
L28 Interceptor Canal							
S190_T	Canal structure	SFWMD	26°16'60"	-80°58'04"	503213.05	2907051.9	Yes
L30 Canal							
S335_H	Canal structure	SFWMD	25°46'34"	-80°28'59"	551839.5	2851000.7	Yes
S335_T	Canal structure	SFWMD	25°46'32"	-80°28'59"	551832.11	2850930.6	Yes
S337_T	Canal structure	SFWMD	25°56'30"	-80°26'28"	555970.78	2869350.6	Yes
L31N Canal							
L31N_1	Canal	USGS	25°44'54"	-80°29'52"	550362.54	2847920.9	Yes
L31N_3	Canal	USGS	25°44'48"	-80°29'51"	550391.1	2847736.4	Yes
L31N_4	Canal	USGS	25°42'07"	-80°29'45"	550577.16	2842784.6	Yes
L31N_5	Canal	USGS	25°41'10"	-80°29'49"	550472.35	2841030.9	Yes
L31N_7	Canal	USGS	25°39'48"	-80°29'53"	550370.42	2838508.1	Yes
L31NN	Canal	SFWMD	25°44'47"	-80°29'51"	550391.22	2847705.7	Yes
L31NS	Canal	SFWMD	25°42'08"	-80°29'45"	550577.04	2842815.4	Yes
G211_H	Canal structure	SFWMD	25°39'36"	-80°29'52"	550398.42	2838121.2	Yes
G211_T	Canal structure	SFWMD	25°39'33"	-80°29'52"	550404.06	2838047.2	Yes
L31W Canal							
S175_H	Canal structure	SFWMD	25°25'05"	-80°34'26"	542862.36	2811294.5	Yes
S175_T	Canal structure	SFWMD	25°25'03"	-80°34'26"	542863.83	2811249.8	Yes
S332D_T	Canal structure	SFWMD	25°28'59"	-80°33'51"	543818.91	2818498.4	Yes
L38E Canal							
S141_T	Canal structure	SFWMD	26°09'03"	-80°26'33"	555712.99	2892496.3	No
S142_H	Canal structure	SFWMD	26°09'37"	-80°26'41"	555489.71	2893543	No
S143_T	Canal structure	SFWMD	26°10'34"	-80°26'54"	555136.92	2895305.4	No
S34_H	Canal structure	SFWMD	26°09'02"	-80°26'33"	555714.5	2892479.6	Yes
S7_T	Canal structure	SFWMD	26°20'07"	-80°32'12"	546248.38	2912887.5	Yes
L39 Canal							
S10A_H	Canal structure	USGS	26°21'36"	-80°18'45"	568592.55	2915744.4	Yes
S10C_H	Canal structure	USGS	26°22'18"	-80°21'09"	564597.91	2917008.9	Yes
S10D_H	Canal structure	USGS	26°23'19"	-80°22'54"	561683.3	2918858.3	Yes
S39_H	Canal structure	SFWMD	26°21'21"	-80°17'53"	570050.07	2915284.6	Yes
L40 Canal							
G300_T	Canal structure	SFWMD	26°40'37"	-80°21'48"	563360.3	2950824	Yes
L6 Canal							
G339_H	Canal structure	SFWMD	26°27'48"	-80°27'09"	554571.68	2927121.8	Yes
G339_T	Canal structure	SFWMD	26°27'48"	-80°27'10"	554557.92	2927099	Yes
L7 Canal							
G301_T	Canal structure	SFWMD	26°40'31"	-80°22'49"	561649.23	2950621.9	Yes
Miami Canal							
S151_H	Canal structure	SFWMD	26°00'42"	-80°30'36"	549024.28	2877054.8	Yes

S151_T	Canal structure	SFWMD	26°00'40"	-80°30'35"	549066.07	2877020.9	Yes
S31_H	Canal structure	SFWMD	25°56'33"	-80°26'26"	556014	2869447.1	Yes
S339_H	Canal structure	SFWMD	26°13'04"	-80°41'27"	530880.38	2899828.6	Yes
S339_T	Canal structure	SFWMD	26°13'01"	-80°41'25"	530927.84	2899756	Yes
S340_H	Canal structure	SFWMD	26°07'09"	-80°36'48"	538669.8	2888945.9	Yes
S340_T	Canal structure	SFWMD	26°07'06"	-80°36'45"	538735.44	2888851.7	Yes
S8_T	Canal structure	USGS	26°19'52"	-80°46'27"	522523.9	2912387.2	Yes
North Feeder Canal							
S190_H	Canal structure	SFWMD	26°17'03"	-80°58'05"	503190.12	2907144.7	Yes
Pennsuco Wetlands							
NWWF	Canal	USGS	25°53'28"	-80°25'13"	558093.5	2863794.9	Yes
S380_H	Canal structure	SFWMD	25°45'41"	-80°26'54"	555313.81	2849371.9	Yes
Tamiami Canal							
G119_H	Canal structure	SFWMD	25°45'40"	-80°28'39"	552405.37	2849342.9	No
G119_T	Canal structure	SFWMD	25°45'40"	-80°28'37"	552454.35	2849344.1	No
S12A_H	Canal structure	USGS	25°45'44"	-80°49'16"	517940.03	2849363.6	Yes
S12B_H	Canal structure	USGS	25°45'44"	-80°46'10"	523115.62	2849372.2	Yes
S12C_H	Canal structure	USGS	25°45'44"	-80°43'37"	527382.65	2849386.2	Yes
S12D_H	Canal structure	USGS	25°45'44"	-80°40'54"	531912.9	2849401.7	Yes
S333_H	Canal structure	SFWMD	25°45'43"	-80°40'27"	532668.15	2849372.8	Yes
S333_T	Canal structure	SFWMD	25°45'42"	-80°40'23"	532774.07	2849335.3	Yes
S334_H	Canal structure	SFWMD	25°45'41"	-80°30'10"	549864.37	2849342.3	Yes
S334_T	Canal structure	SFWMD	25°45'41"	-80°30'05"	549992.45	2849340.4	Yes
S336_H	Canal structure	SFWMD	25°45'40"	-80°29'50"	550405.97	2849339.8	Yes
S336_T	Canal structure	SFWMD	25°45'40"	-80°29'48"	550486.99	2849335.3	Yes
Water Conservation Area 3A							
S140_T	Canal structure	SFWMD	26°10'18"	-80°49'38"	517275.03	2894702.9	Yes

Appendix B: EDEN NetCDF Data Format

NetCDF (Network Common Data Form) is a set of freely-distributed software libraries and machine-independent binary data formats that support the creation, access, and sharing of large array-oriented scientific data. This format replaces the bulky file structure and difficult file management of ESRI GRIDS for EDEN data. It also allows EDEN applications to run on computers without ArcGIS installations.

NetCDF was originally created for climatological datasets and is used by groups such as NOAA, Los Alamos National Laboratory, and Woods Hole Oceanographic Institution. The netCDF software was developed out of the NASA CDF data model by the Unidata Program Center, sponsored by the National Science Foundation, and with contributions from the netCDF user community. An increasing number of commercial and free software applications and utilities support netCDF including ESRI ArcGIS(as of version 9.2) and MATLAB. Some of the features of netCDF that add to its popularity include:

1. Support for time-series of array-oriented data sets
2. Direct access of data allows for efficient access of small subsets of large datasets
3. A netCDF file can be self-describing. That is, it can include information about the data it contains
4. NetCDF files are portable and can be accessed by computers with different methods of storing values
5. One writer and multiple readers may simultaneously access the same netCDF file in a shared network
6. Data may be appended to a properly structured netCDF file without copying the dataset or redefining its structure

ArcGIS users can easily use EDEN netCDF datasets. EDEN netCDF datasets follow the climate and forecasting (CF) metadata conventions which specify spatial and temporal attributes included in the files (Table 1). This is the critical element in netCDF that allows integration with geographic information systems (GIS) such as ArcGIS. ArcGIS (versions 9.2 and later) has the ability to read CF-compliant netCDF files.

The most important thing for users to know about EDEN water stage data files is that each file contains 3 months (a quarter) of daily datasets. So, for example, the data for every day in 2002 will be stored in 4 files: 2002_q1.nc, 2002_q2.nc, 2002_q3.nc, and 2002_q4.nc. The digital elevation model, which is necessary for the creation of EDEN water depth datasets, is contained in a file named dem.nc.

The JEM (Joint Ecological Modeling) Lab at the University of Florida, Fort Lauderdale Research and Education Center provides utilities for the viewing and analysis of EDEN netCDF files.

Table B1. CF-compliant metadata in the header of EDEN water stage netCDF files provide spatial information for projecting the data in a GIS, as well as the start date and time step for the time-series of data in the file.

Attribute	Example Value in EDEN stage data files
Creation Date	June 1, 2007
Conventions	CF-1.0
Source	JEM NetCDF writer
Layer name	stage
Layer Version	1.1
Spatial Reference	NAD_1983_UTM_Zone_17N
Datum	North_American_1983
Spheroid	GRS_1980
Prime Meridian	Greenwich, 0.0
Angular Units	Degree (0.0174532925199433)
Projection	Transverse_Mercator
Linear Units	Meter (1.0)
False Easting	500000.0
False Northing	0.0
Central Meridian	-81.0
Scale Factor	0.9996
Latitude of Origin	0.0
Grid Mapping Units	cm
Starting Date	2000-01-01T12:00:00Z
Time Step Units	days

Additional sources of information

About netCDF: <http://www.unidata.ucar.edu/software/netcdf/>

About CF Conventions: <http://www.cgd.ucar.edu/cms/eaton/cf-metadata/CF-current.html>

Appendix C: Constructing Confidence Index Maps for Interpolated Water Surface

The final confidence index map for an interpolated water surface is a geometric mean of these attributes:

Canal Index – The closer a grid cell is to a canal the lower the confidence.

Error Index – Is derived from cross validation errors computed by the water surface model for each station that had data. The error represents the difference between measured and predicted water level for a station, where the lower the error the higher the confidence. Thiessen polygons created for each station with data are used to project cross-validation errors at a station (point information) to a spatial extent representing the influence of a station on its surrounding area.

Distance Index – Composed of multiple ring buffers placed around stations with data. The distance index represents the distance to the nearest station; up to 10 rings can be placed around a station with each ring representing 1000 meters. The closer a grid cell is to a station the higher the confidence at that grid cell.

Create Canal Index

This feature class will be used for determining confidence index values depending on how close a grid cell on the predicted surface is to a canal (i.e. least confidence when within 0 to 1000 meters of a canal; mid confidence when within 1000 to 2000 meters of a canal; most confidence when beyond 2000 meters of a canal.

Because the location of canals doesn't normally move, this index layer only needs to be created one time. Daily confidence indices can all use the same canal index.

A multiple ring buffer is created around a shapefile of canals. The buffer distances are 1000 and 2000m.

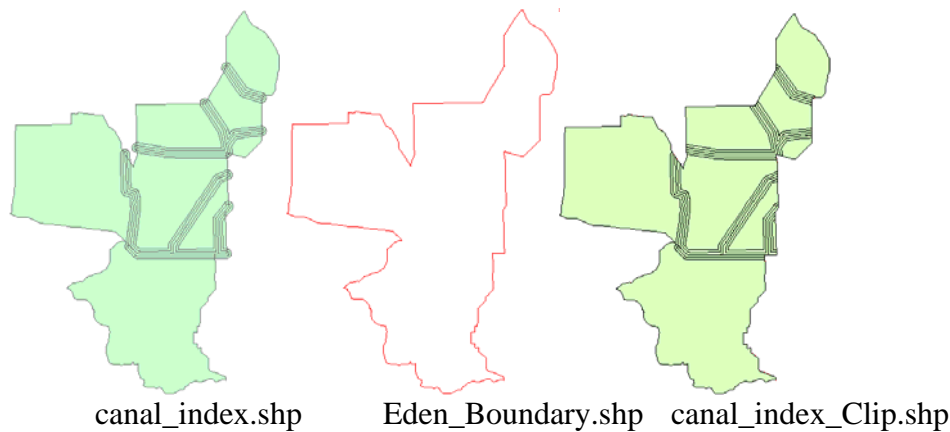
Index values are assigned to a new field in the table for the new buffer layer such that

If buffer distance > 2000 then Canal_index = 1

If buffer distance = 2000 then Canal_index = 0.5

If buffer distance = 1000 then Canal_index = 0.01

The canal index buffer shapefile is then clipped to the EDEN boundary.



Create Error Index

This feature class will be used for determining confidence index values depending on cross-validation errors of the closest water stage gage to a grid cell on the predicted surface.

Add XY data for the daily median txt file for all stations operating on the particular day being indexed.

Append the fields from the cross validation table to the median shapefile (in ArcGIS on the Join Data dialog box, this is option 2, Each point will be given all the attributes...”).

Remove all stations that are not used to create the final confidence index. The final confidence index is based just on EDEN stations not used in canal linear interpolation or certain outlier stations that may unjustly skew the confidence.

Excluded from processing, the final confidence index dataset are canal interpolation (i.e., S10A-UP), some outlier stations (i.e., BCA10+) that had data on the date being processed and coastal stations. Appendix A lists all the gaging stations and notes the canal stations. Excluded stations are listed in Table C1.

Create absolute cross-validation error index

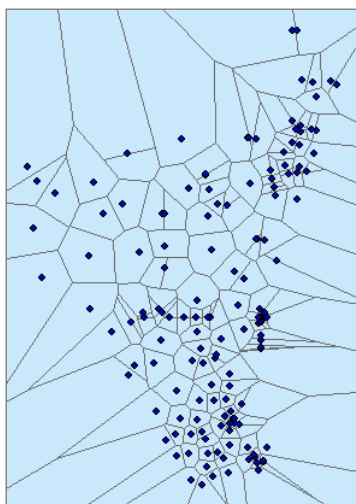
In the just created stations shapefile with unused stations removed, index values are assigned to a new field such that:

```
If Abs ( [Error] ) <= 5 then CV_index = 1
If Abs ( [Error] ) > 5 and Abs ( [Error] ) <= 10 then CV_index = 0.8
If Abs ( [Error] ) > 10 and Abs ( [Error] ) <= 15 then CV_index = 0.6
If Abs ( [Error] ) > 15 and Abs ( [Error] ) <= 20 then CV_index = 0.4
If Abs ( [Error] ) > 20 and Abs ( [Error] ) <= 25 then CV_index = 0.2
If Abs ( [Error] ) > 25 then CV_index = 0.01
```

where $\text{Abs}(\{\text{Error}\})$ is the absolute value of the cross-validation error.

Table C1. Water stage stations excluded from the cross-validation error confidence index.

Station	Area
BCA10+	BCNP
BCA11+	BCNP
BCA19+	BCNP
LOOP2+H	BCNP
LOOP2+T	BCNP
EVER8	ENP
S332D-T	L31W Canal
L31W	ENP
MCCORMICK	Florida Bay
TAYLORRIVER	Florida Bay
MUD	Florida Bay
TAYLOR_UP	Florida Bay
TROUT	Florida Bay
STILLWATER	Florida Bay



Create Thiessen Polygons From Point (stations) Layer

Thiessen polygon layer is created from the station point layer. The resulting Thiessen polygon layer is created with the same attributes as the point coverage layer including the error index.

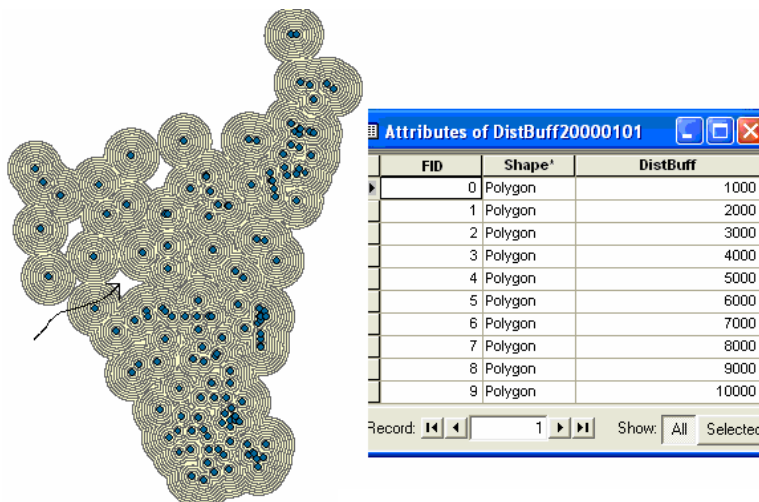
Create Distance Buffer Layer

This feature class will be used for determining confidence index values depending on how close a grid cell on the predicted surface is to water stage monitoring stations.

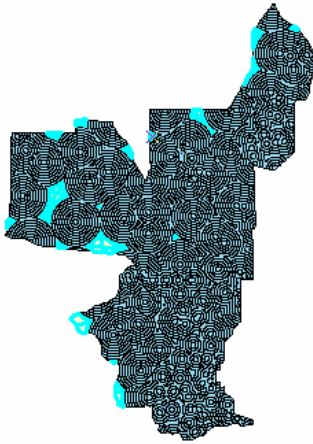
The distance layer is based on the “distance to the nearest station”. This will be done by creating multiple ring buffers around stations with data and using distance values of 1000, 2000, 3000, 4000, 5000, 6000, 7000, 8000, 9000, and 10000 meters from the nearest station. Overlapping boundaries are dissolved.

Input is the station point layer,

Clip the multi ring distance buffer layer using the Eden boundary.



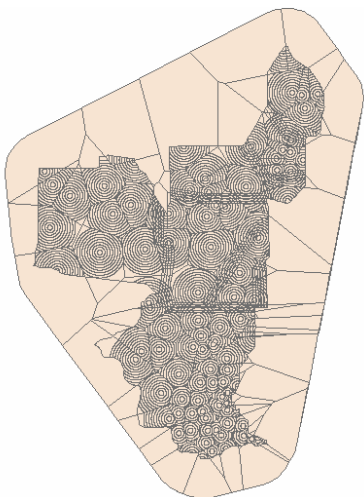
The distance buffers will be used to generate the distance index, but not until after the distance buffer is combined with the canal index and error index. If the distance index was calculated from the distance buffer at this point, then some of the areas would not have a distance index:



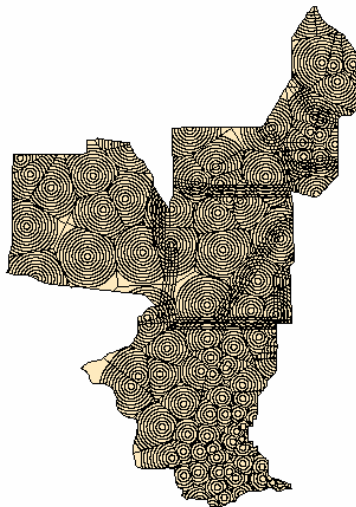
highlighted areas wouldn't have a distance index

Combine the Index Layers

Use the Union command to overlay the two index layers (canal and error) and distance buffer layer. Their attribute tables can not be joined because they all have different numbers of records and none of them have a field in common such as a station name. The union is clipped to the EDEN boundary.



Union



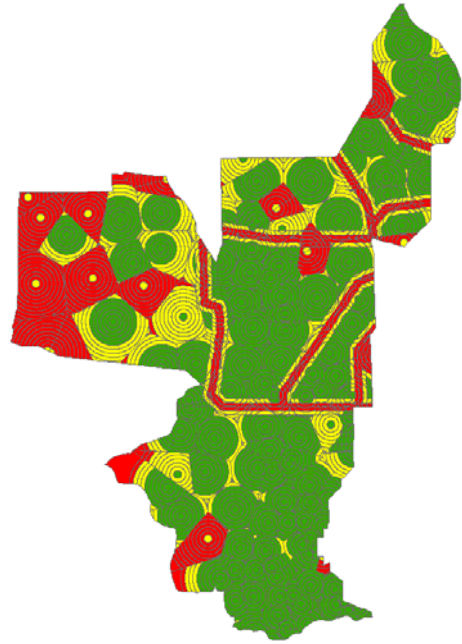
Clipped

Calculate Distance Index

Now that all index layers have been combined into one layer and all possible polygons have been created, the distance index can be correctly calculated.

For the combined layer, index values are assigned to a new field in the table such that:

If [DistBuff] > 0 and [DistBuff] <= 1000
then index = 1
If [DistBuff] > 1000 and [DistBuff] <= 2000
then Dist_index = 0.9
If [DistBuff] > 2000 and [DistBuff] <= 3000
then Dist_index = 0.8
If [DistBuff] > 3000 and [DistBuff] <= 4000
then Dist_index = 0.7
If [DistBuff] > 4000 and [DistBuff] <= 5000
then Dist_index = 0.6
If [DistBuff] > 5000 and [DistBuff] <= 6000 then Dist_index = 0.5
If [DistBuff] > 6000 and [DistBuff] <= 7000 then Dist_index = 0.4
If [DistBuff] > 7000 and [DistBuff] <= 8000 then Dist_index = 0.3
If [DistBuff] > 8000 and [DistBuff] <= 9000 then Dist_index = 0.2
If [DistBuff] > 9000 or [DistBuff] = 0 then Dist_index = 0.1



Create Final Confidence Index

For the combined layer, index values are assigned to a new field in the table so that:

$$C = (Canal_index)^{2/5} * (Dist_index)^{2/5} * (CV_index)^{1/5}$$

The weighted geometric mean assigns more weight to the distance and canal indexes than to the cross validation error index. Less weight is assigned to this last index because it is based on predicted water level values when removing a station that is actually present that day. This skews the result less favorably for areas in close proximity, and directly at, a gage station.

Transform the index to qualitative terms.

Add a new field to the final table such that:

If [C] <= 0.39 then index = "Low"
If [C] > 0.39 and [C] <= 0.69 then index = "Medium"
If [C] > 0.69 then index = "High"

Confidence Index

